



Invertebrate Learning and Memory: Chapter 8. Issues in Invertebrate Learning Raised by Robot Models (Handbook of Behavioral Neuroscience)

Barbara Webb

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A robot that senses and interacts autonomously with the real world can be used to embody specific hypotheses about the mechanisms of learning in invertebrates. Several models of olfactory learning circuits in the mushroom body of flies have been proposed. To use this to control a robot, it is crucial to understand not only when and how changes in synaptic strength occur but also how those synaptic changes fit within a circuit that produces ongoing behavior. Considering this problem from a robotic perspective reveals some conflicting assumptions made in current research that need to be resolved.

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